



SAFETY TORQUE SENSORS

CUSTOM TORQUE SENSOR FOR INTEGRATED AND IMPROVED FUNCTIONAL SAFETY IN COLLABORATIVE ROBOTS

High Functional Safety

TE Connectivity's (TE) safety torque sensor has been designed to meet functional safety requirements up to ISO13849 Category 3 PL d thanks to two electrically segregated channels with no common cause failure. In addition, high overload capability helps prevent device failure.

Low Susceptibility to Cross Loads

Our safety torque sensor has been primarily designed for collaborative robot applications and to be assembled on Harmonic Drive gear boxes that result in highly complex stress state. The sensor design is then optimized to reduce axial, radial load and tilting moment susceptibility providing increased accuracy.

Customizable Mechanical Interface

Systems like robots require highly integrated components and our safety torque sensor is available with customized mechanical interfaces. The basic concept of the sensor is always the same (low profile sensor with overall height lower than 20mm) but it can be easily adapted in terms of size and sensing range to meet customer application requirements. If needed, the sensor can be used as a sealing wall to seal a gear box.

Digital I²C Electrical Interface

The standard electrical interface is an I²C serial digital interface with 400kHz communication rate allowing ease of integration.

Innovative Microfused Technology

Microfused technology eliminates age-sensitive organic epoxies used in traditional load cell designs, thus providing excellent long-term span and zero stability because potential problems with resin ageing are avoided.

Strain gages are bonded to the mechanical part using innovative Microfused technology from TE. This technology is based on micromachining silicon piezo-resistive strain gages and fusing them in a high-temperature glass-bonding process to a high-performance stainless-steel substrate. This very mature and reliable process has delivered millions of force sensors, which are well proven

Applications

- Collaborative robot joints for functional safety
- Low profile sensor for integration in various industrial systems requiring safe torque control

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SPECIFICATIONS

Torque range	From 20Nm to 900Nm (14.7 ft-lbf to 664 ft-lbf)
Dimension	Outer diameter: from 65mm (2.56in) minimum to 140mm (5.51in) typically (smallest diameters are limited by torque transmission capabilities). Overall height: 20mm (0.79in) typ.
Materials	High strength stainless steel (17-4PH) or Titanium (Ti-6Al-4V) housing and FR4 PCB.
Mass	Depending on interface requirements and material, typical value for 100 Nm (73.7 ft-lbf) range is less than 200 gr (0.4 lb).
Overload	±300% of nominal torque range.
Structural torque	±500% of nominal torque range.
Stiffness	> 100 000 Nm/rad (73 600 F ft-lbf/rad)
Non-Linearity	±0.25%FS maximum.
Hysteresis	±0.25%FS maximum.
Resolution	0.025%FS maximum.
Temperature	0°C to +85°C compensated range. -40°C to +105°C operating range.
Overall accuracy	±1.5%FS typ. including Non-linearity, Hysteresis, Span setting and Thermal drifts.
Channel difference	±2%FS typ. including Non-linearity, Hysteresis, Span setting and thermal drifts.
Cross loads susceptibility	Axial load: ±0.2%FS typ. (axial load is equivalent to torque range, 100N for 100Nm range) Radial load: ±0.2%FS typ. (radial load is equivalent to torque range, 100N for 100Nm range) 1%FS tilting moment: ±0.2%FS typ. (higher loads or tilting moment would require thicker sensor)
Power supply	5 Vdc ± 0.15 Vdc typ.
Current consumption	< 10 mA per channel.
Electrical interface	I ² C.
Digital output	16 Bit output register.

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Bandwidth 1000 Hz minimum.

Communication rate I²C: 400 kHz maximum

Environmental spec. capability Vibration, shock, temperature, humidity acc. to EN 60068.
EMC (ESD, radiated field immunity, surge immunity) acc. to EN 61000-4.

Ordering Information

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